4F5: Advanced Wireless Communications

Handout 7: Characterisation of Fading Channels

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Advanced Wireless Communications

Lent 2012 1 / 12



Multipath Fading Channels

- Let α_n denote the attenuation of path *n*, and let τ_n denote its delay.
- Transmitter, receiver, scatterers move: α_n and τ_n are time-varying.
- Let $x_l(\cdot)$ be the baseband equivalent of $x(\cdot)$, i.e., $x(t) = \text{Re}\{x_l(t)e^{j2\pi t_c t}\}$:

$$y(t) = \sum_{n} \alpha_{n}(t) x(t - \tau_{n}(t)) + n(t)$$

= Re $\left\{ \left[\sum_{n} \alpha_{n}(t) e^{-j2\pi f_{c}\tau_{n}(t)} x_{l}(t - \tau_{n}(t)) + n'(t) \right] e^{j2\pi f_{c}t} \right\}$

• Suppose that $\tau_n(t)$ varies only little:

 $x(t - au_n(t)) pprox x(t - au_n)$ and $2\pi f_c au_n(t) = heta_n(t)$ (since f_c is large

• Then, the baseband equivalent received signal is

$$y_l(t) = \sum_n \alpha_n(t) e^{-j\theta_n(t)} x_l(t-\tau_n) + n'(t) \quad \longrightarrow \quad y_l(t) = \int h(t;\tau) x_l(t-\tau) d\tau + n'(t)$$

as the number of paths tends to infinity.

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- Paths may add constructively or destructively: large fluctuations possible.
- Path attenuations and delays are deterministic.
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Image: A matrix

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Channel Correlation Functions and Power Spectra

Time-varying impulse response h(t; τ) is modelled as complex random process.
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 (h(t₁, τ), t ∈ R) is wide sense stationary, i.e., E[h(t₁; τ)] does not depend on t,
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 Scatterers are uncorrelated, so

$R_h(t_1, t_2; \tau_1, \tau_2) = R_h(t_1, t_2; \tau_1, \tau_1) \delta(\tau_2 - \tau_1)$

- *R_h*(τ) ≜ *R_h*(0, 0; τ, τ) is called the delay power spectrum. It describes the average power of the path attenuation as a function of τ.
- The range of values of τ over which R_h(τ) > 0 is called the delay spread T_d. It
 indicates the amount of temporal broadening due to multipath propagation.



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- Time-varying impulse response $h(t; \tau)$ is modelled as complex random process.
- Let $R_h(t_1, t_2; \tau_1, \tau_2) \triangleq \mathbb{E}[h(t_1; \tau_1)^* h(t_2; \tau_2)]$. The WSSUS assumption is: $\{h(t; \tau), t \in \mathbb{R}\}$ is wide sense stationary, i.e., $\mathbb{E}[h(t; \tau)]$ does not depend on t, $R_h(t_1, t_2; \tau_1, \tau_2) = R_h(t_1 - t_2, 0; \tau_1, \tau_2)$ and $R_h(0, 0; \tau_1, \tau_2) < \infty$ Scatterers are uncorrelated, so

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Channel Correlation Functions and Power Spectra

Let

$$S_H(\xi; \Delta f) \triangleq \int R_H(\Delta t, 0; \Delta f, 0) e^{-j2\pi\xi\Delta t} d\Delta t \text{ and } S_H(\xi) \triangleq S_H(\xi; 0)$$

- $S_H(\xi)$ is called the Doppler power spectrum. It indicates the amount of spectral broadening in the received signal due to Doppler shift.
- If the channel is time-invariant, then $R_H(t_1, t_2; f_1, f_1) = 1$ and $S_H(\xi) = \delta(\xi)$.
- The range of frequencies ξ such that $S_H(\xi) > 0$ is called the Doppler spread B_d .

• We define the coherence time of the channel as $T_c \triangleq \frac{1}{B_d}$.

• Let T be the duration of the transmitted codeword. If $T > T_c$, then the channel is said to be time-selective (fast), and if $T \ll T_c$, then it is said to be time-flat (slow).



Channel Correlation Functions and Power Spectra

Let

$$S_H(\xi; \Delta f) \triangleq \int R_H(\Delta t, 0; \Delta f, 0) e^{-j2\pi\xi\Delta t} d\Delta t \text{ and } S_H(\xi) \triangleq S_H(\xi; 0)$$

- $S_H(\xi)$ is called the Doppler power spectrum. It indicates the amount of spectral broadening in the received signal due to Doppler shift.
- If the channel is time-invariant, then $R_H(t_1, t_2; f_1, f_1) = 1$ and $S_H(\xi) = \delta(\xi)$.
- The range of frequencies ξ such that $S_H(\xi) > 0$ is called the **Doppler spread** B_d .

• We define the coherence time of the channel as $T_c \triangleq \frac{1}{B_d}$.

• Let T be the duration of the transmitted codeword. If $T > T_c$, then the channel is said to be time-selective (fast), and if $T \ll T_c$, then it is said to be time-flat (slow).



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Example

- Mobile radio channels depend critically on the type of terrain.
- Urban and suburban areas: $T_d \approx 1 10\mu$ s.
- Rural, hilly areas: $T_d \approx 10 30 \mu s$.
- A widely used model for the Doppler power spectrum is Jakes' model

$$S_{H}(\xi) = egin{cases} rac{1}{\pi f_{m}} rac{1}{\sqrt{1 - (\xi/f_{m})^{2}}} & |\xi| < f_{m} \ 0 & |\xi| \ge f_{m} \end{cases}$$

where $f_m = v f_c / c$ is the maximum Doppler frequency, v is the speed in m/s, f_c is the carrier frequency and c is the speed of light.



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Classification of Fading Channels

Let T be the codeword duration, and let B be the signal bandwidth:



Classification of Fading Channels

- Whether channel is selective in time/frequency depends on the statistics of the channel **and** the transmitted signal.
- If $T_c B_c > 1$ then the channel is said to be underspread, and if $T_c B_c \ll 1$ then it is said to be overspread.



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From Continuous-Time to Discrete-Time

• Continuous-time fading model:

$$y_l(t) = \int h(t;\tau) x_l(t-\tau) \mathrm{d}\tau + n'(t), \qquad t \in \mathbb{R}$$

$$y_i = \sum_{\ell=0}^{N_p-1} h_{i,\ell} x_{i-\ell} + n_i, \qquad i = 1, 2, \dots$$

- Each path $h_{i,\ell}$ summarises the contribution of multiple scatterers within a symbol period T_s .
- Often paths are modelled as complex Gaussian random variables with variance $\sigma_n^2 = |R_h(nT_s)|^2$. This is "justified" by the central limit theorem.
- Other models can be used to better fit experimental data, e.g., Nakagami-m.



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Flat Fading

Only one tap, i.e., $N_p = 1$:

$$y_i = h_i x_i + n_i, \qquad i = 1, 2, \dots$$

No ISI.

Slow fading: h_i does not depend on i.

• Fast fading: h_1, h_2, \ldots are i.i.d.

Frequency-Selective Fading

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